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**Computer Science and Engineering** 



# Finite element model for a viscous incompressible fluid flow

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### **ARTICLE INFO**

Article history: Received: 26 December 2011; Received in revised form: 22 January 2012; Accepted: 2 February 2012;

#### Keywords

Finite element model, Viscous incompressible fluid flow, Pressure, Velocity fields, Penalty parameter.

## Introduction

## **Problem Statement**

Flow of a viscous lubricant in a slider bearing; the slider (or slipper) bearing consists of a short sliding pad moving at a velocity  $u=U_o$  relative to a stationary pad inclined at a small angle with respect to the stationary pad and the small gap between the two gaps is filled with a lubricant (which is given in figure 1). Since the ends of the bearing are generally open, the pressure Po there is atmospheric. If the upper pad is parallel to the base plate, the pressure everywhere in the gap must be atmospheric (because dP/dx is a constant for flow between parallel plates) and the bearing cannot support any transverse load. If the upper pad is inclined to the base pad, a pressure distribution (in general, a function of x and y) is set up in the gap. For large values of  $U_o$ , the pressure generated can be of sufficient magnitude to support heavy loads normal to the base pad.



Figure 1. The geometry and boundary conditions of a slider bearing

Input data of the problem for various penalty parameters in 8x8 and 16x8 meshes are given. The necessary equation and data are as follows;

$$\frac{dP}{dx} = \mu \frac{\partial^2 u}{\partial y^2} \qquad u = u(x, y) \qquad (1)$$

$$h_1 = 2h_2 = 8x10^{-4} ft$$

$$L = 0.36 ft$$

$$\mu = 8x10^{-4} lb / ft^2$$

$$V_0 = 30$$

### ABSTRACT

In this paper, finite element model for flow of a viscous lubricant in a slider bearing is considered as a problem. For this problem, two different types of finite element models have been presented which are the velocity-pressure finite element model, with (u,v,P) as the primary nodal degrees of freedom and the penalty finite element model with (u,v) as the primary nodal degrees of freedom. Quadrilateral elements are used since they are more reliable for pressure as well as for velocity fields in the penalty finite element model.

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#### Initial Condition:

Uy = 0

By using these data and equation (1), viscous flow problem is solved by using an 8x8 mesh of 4 node quadrilateral elements and 16x8 (16 in x direction) elements. The effects of the various penalty parameters (such as  $10^2$ ,  $10^3$ ,  $10^4$ ,  $10^5$ , 106, and 1011) on the velocity and pressure fields are also investigated. A program written in FORTRAN is used.

#### **Modeling Considerations**

To solve this problem by finite element method, 8x8 mesh of 4 node quadrilateral elements and 16x8 (16 in x direction) elements are employed. For these meshes, nodes numbering of the system are given in figure 2 and 3, respectively.



Figure 2.Finite element model for 8x8 meshes of linear quadrilateral elements



## Figure 3.Finite element model for 16x8 meshes of linear quadrilateral elements

**Finite Element Solution of the problem** It should be pointed out that the assumption concerning the

pressure not being a function of y is not necessary in the finite

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element analysis. First, a mesh of 8x8 linear quadrilateral elements is used to analyze the problem. The boundary conditions are given in Figure 1. Finally to obtain more accurate solutions, a graded mesh of 128 linear quadrilateral elements is employed.

#### Solution of the problem for 8x8 mesh

Influence of the penalty parameter on the variation of the pressure and velocity values along the length of the slider bearing can be illustrated in the following figures:



Figure 4. The comparison of results with respect to pressure values for penalty parameters such as  $10^{2}$ ,  $10^{3}$ ,  $10^{4}$ ,  $10^{5}$ ,  $10^{6}$ 



Figure 5. The comparison of results with respect to pressure values for penalty parameters such as  $10^{2}$ ,  $10^{3}$ ,  $10^{5}$ ,  $10^{11}$ .



Figure 6. The comparison of results with respect to velocity values for penalty parameters such as  $10^{2}$ ,  $10^{3}$ ,  $10^{5}$ - $10^{11}$ .



Figure 7. The comparison of results with respect to velocity values for penalty parameters such as  $10^{2}$ ,  $10^{4}$ ,  $10^{5}$ - $10^{11}$ . Solution of the problem for 16x8 mesh

Influence of the penalty parameter on the variation of the pressure and velocity values along the length of the slider bearing can be illustrated in the following figures:



Figure 8. The comparison of results with respect to pressure values for penalty parameters such as  $10^{2}$ ,  $10^{3}$ ,  $10^{4}$ ,  $10^{5}$ , and  $10^{6}$ 



Figure 9. The comparison of results with respect to pressure values for penalty parameters such as  $10^{2}$ ,  $10^{4}$ ,  $10^{5}$ - $10^{11}$ .



Figure 10. The comparison of results with respect to velocity values for penalty parameters such as  $10^{2}$ ,  $10^{4}$ ,  $10^{5}$ -  $10^{11}$ .



Figure 11. The comparison of results with respect to velocity values for penalty parameters such as  $10^{2}$ ,  $10^{4}$ ,  $10^{5}$ - $10^{11}$ . Comparison of the results between 8x8 and 16x8 meshes for penalty parameter  $10^{5}$ 

Influence of the penalty parameter  $10^5$  on the variation of the pressure and velocity values along the length of the slider bearing in order to compare the results between 8x8 and 16x8 meshes, can be illustrated in the following figures:



Figure 12. The comparison of results with respect to pressure values for 16x8 and 8x8 mesh element with penalty parameter 10<sup>5</sup>



Figure 13. The comparison of results with respect to velocity values for 16x8 and 8x8 mesh element with penalty parameter 10<sup>5</sup>

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#### **Results and Conclusions**

Different penalty factor shows that when the penalty factor increases oscillation has higher amplitude than the lower one. Different values for penalty parameter are examined to investigate the effect on the solution results. The sensitivity of results is investigated.

In conclusion, it is clearly seen from figures and results that if penalty parameter is chosen in range between  $10^{5}$ - $10^{11}$  give same results. Therefore it can be said that if the penalty parameter is between  $10^{5}$ - $10^{11}$ , better approximation is obtained. In addition it can be said that there is a slight difference in between 8x8 and 16x8 meshes in V<sub>x</sub> values. However for pressure values the difference is higher.

Finally finite element model 16x8 gives better approximation in between penalty parameter range  $10^5$ - $10^{11}$ . By

increasing number of mesh elements, it is obvious that better approximations which are close to exact solution can be obtained.

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