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Conformal Lagrangian Dynamics on Contact 9- Manifolds

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ABSTRACT

In this study, we concluded the Conformal Lagrangian Dynamics on (TM, ξ, J) , being a model. Finally introduce, some geometrical and physical results on the related mechanic systems have been discussed.

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1. Introduction

Differential geometry is a rich and beautiful field in pure mathematics whose origins lie in classical physics. Specifically, Contact spaces arose as the natural setting in which to study Lagrangian mechanics . A Contact structure is precisely what is needed to associate a dynamical system on the space to each energy function.

It is the most important studies on the subject of paper is a study entitled (Lagrangian Mechanics on Contact 5- Manifolds)

In the study entitled conformal Euler-Lagrange mechanical on contact 5- Manifolds , presents Lagrangian Mechanics on contact 5- manifolds. In the end, the some results related to contact 5- manifolds. dynamical systems are also discussed

The paper is structured as follows. In second 2, we review contact 5- manifolds. In second 3 we introduce Lagrangian equations for dynamical systems on contact 5- manifold .In conclusion, we discuss some geometric-physical results about Lagrangian equations and fields constructed on the base manifolds

2. Contact 9- Manifolds

Definition 2-1 [2]

Let M be a manifold of odd dimension (2n+1) and ξ field The pair (M, ξ) Is called a contact manifold

Theorem 2-2. A conformal manifold is a differentiable manifold equipped with an equivalence class of Riemann metric tensors, in which two f_1 metrics f_2 and are equivalent if and only if (1)

$$f_2 = B^2 f_1$$

where is a smooth positive function. B > 0

Theorem 2.3

.[1] A conformal transformation is a change of coordinates such that the metric changes by $\sigma^a \rightarrow \sigma^b$ $f_{ab}(\sigma) \rightarrow B^2(\sigma) f_{ab}(\sigma)$

Theorem 2.4

Let $\left(\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_2}\right)$ bases on manifold, **J** Conformal to the structure coefficient

$$J\left(\frac{\partial}{\partial x_{1}}\right) = B^{2}\cos\theta\left(\frac{\partial}{\partial x_{5}}\right) + B^{2}\sin\theta\left(\frac{\partial}{\partial x_{6}}\right) \qquad , J\left(\frac{\partial}{\partial x_{2}}\right) = B^{2}\cos\theta\left(\frac{\partial}{\partial x_{6}}\right) + B^{2}\sin\theta\left(\frac{\partial}{\partial x_{5}}\right)$$
$$J\left(\frac{\partial}{\partial x_{3}}\right) = -B^{2}\cos\theta\left(\frac{\partial}{\partial x_{7}}\right) + B^{2}\sin\theta\left(\frac{\partial}{\partial x_{8}}\right) , \qquad J\left(\frac{\partial}{\partial x_{4}}\right) = -B^{2}\cos\theta\left(\frac{\partial}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial}{\partial x_{7}}\right)$$
$$J\left(\frac{\partial}{\partial x_{5}}\right) = -B^{-2}\cos\theta\left(\frac{\partial}{\partial x_{1}}\right) - B^{-2}\sin\theta\left(\frac{\partial}{\partial x_{2}}\right) , \qquad J\left(\frac{\partial}{\partial x_{6}}\right) = B^{-2}\cos\theta\left(\frac{\partial}{\partial x_{2}}\right) - B^{-2}\sin\theta\left(\frac{\partial}{\partial x_{1}}\right)$$
$$J\left(\frac{\partial}{\partial x_{7}}\right) = -B^{-2}\cos\theta\left(\frac{\partial}{\partial x_{3}}\right) - B^{-2}\sin\theta\left(\frac{\partial}{\partial x_{4}}\right) , \qquad J\left(\frac{\partial}{\partial x_{8}}\right) = B^{-2}\cos\theta\left(\frac{\partial}{\partial x_{4}}\right) - B^{-2}\sin\theta\left(\frac{\partial}{\partial x_{1}}\right)$$

3. Lagrangian Dynamics

Definition 3.1 [1].

A Lagrangian function for a Hamiltonian vector field $\boldsymbol{\xi}$ on M is a smooth function L : TM \rightarrow R such that

 $i_{\xi}\omega_{L} = dE_{L}$

Kinetic energy given $T: M \to R$ such that

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47333 Ibrahim Yousif .I. Abad alrhman and Abdul Aziz .B. M. Hamed / Elixir Appl. Math. 107C (2017) 47332-47338 $T = \frac{1}{2}m_i(\dot{x}_1^2 + \dot{x}_2^2 + \dot{x}_3^2 + \dot{x}_4^2 + \dot{x}_5^2 + \dot{x}_6^2 + \dot{x}_7^2 + \dot{x}_8^2)$ Potential energy $P: M \rightarrow R$ such that $P = m_i gh$ (5) $m_i = mass$ andh = stand, g = gravity acceleration

The Lagrangian function $L: \mathbb{R}^{10n} \to \mathbb{R}$ is map that satisfies the condition then

 $\mathbf{L} = \mathbf{T} - \mathbf{P}$

Definition 3.2 [2].

A Lagrangian system is a triple $(M; \xi)$, where $(\omega; L)$ is a Symplectic manifold and $L \in C^{\infty}(M)$ is a function, called the Hamiltonian function.

(6)

Theorem 3.3

Let M be m-real dimensional configuration manifold .A tensor field J on TM is called an almost complex structure on TM if at every point p of TM, J is endomorphism of the tangent space $T_n(M)$ such that $J^2 = -1$ are complex is

$$J^{2}\left(\frac{\partial}{\partial x_{i}}\right) = -\frac{\partial}{\partial x_{i}} \qquad i = 1, 2, 3, 4, 5, 6, 7, 8$$
(7) J is called almost complex manifold
$$(7)$$

Proposition 3.4

Let λ be the vector field characterized by

$$\lambda = \sum_{i=1}^{8} \left(X^{i} \frac{\partial}{\partial x_{i}} \right) \qquad X^{i} = \dot{x}^{i}$$

$$(B)$$

$$(TM, g, J) \text{ then vector field defined by}$$

$$J(\lambda) = J \left(\sum_{i=1}^{8} \left(X^{i} \frac{\partial}{\partial x_{i}} \right) \right) = \sum_{i=1}^{8} X^{i} J \left(\frac{\partial}{\partial x_{i}} \right)$$

$$J(\lambda) = X^{1} J \left(\frac{\partial}{\partial x_{1}} \right) + X^{2} J \left(\frac{\partial}{\partial x_{2}} \right) + X^{3} J \left(\frac{\partial}{\partial x_{3}} \right) + X^{4} J \left(\frac{\partial}{\partial x_{4}} \right) + X^{5} J \left(\frac{\partial}{\partial x_{5}} \right) + X^{6} J \left(\frac{\partial}{\partial x_{6}} \right) + X^{7} J \left(\frac{\partial}{\partial x_{7}} \right) + X^{8} J \left(\frac{\partial}{\partial x_{8}} \right)$$

$$J(\lambda) = X^{1} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{5}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{6}} \right) \right) + X^{2} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{6}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{5}} \right) \right) + X^{3} J \left(-B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{6}} \right) - B^{2} \sin \theta \left(\frac{\partial}{\partial x_{5}} \right) \right) + X^{3} J \left(-B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{6}} \right) - B^{2} \sin \theta \left(\frac{\partial}{\partial x_{5}} \right) \right) + X^{3} J \left(-B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{6}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{7}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{8}} \right) \right) + X^{5} J \left(B^{2} \cos \theta \left(\frac{\partial}{\partial x_{8}} \right) \right)$$

$$X^{4}J\left(-B^{2}\cos\theta\left(\frac{\partial}{\partial x_{8}}\right)+B^{2}\sin\theta\left(\frac{\partial}{\partial x_{7}}\right)\right)+X^{5}J\left(-B^{-2}\cos\theta\left(\frac{\partial}{\partial x_{1}}\right)-B^{-2}\sin\theta\left(\frac{\partial}{\partial x_{2}}\right)\right)+X^{6}J\left(B^{-2}\cos\theta\left(\frac{\partial}{\partial x_{2}}\right)-B^{-2}\sin\theta\left(\frac{\partial}{\partial x_{1}}\right)\right)+X^{7}J\left(-B^{-2}\cos\theta\left(\frac{\partial}{\partial x_{3}}\right)-B^{-2}\sin\theta\left(\frac{\partial}{\partial x_{4}}\right)\right)+X^{8}J\left(B^{-2}\cos\theta\left(\frac{\partial}{\partial x_{4}}\right)-B^{-2}\sin\theta\left(\frac{\partial}{\partial x_{3}}\right)\right)$$

Liouville vector field on contact 9-manifold (TM, g, J).then vector field defined by energy function given by

$$E_L^{G_1} = U_{G_1}(L) - L$$

is vertical derivation (differentiation) $\mathbf{d}_{\mathbf{G}_{i}}$

is defined

The

$$\begin{aligned} & d_{G_{1}} = [\iota_{G_{1}}, u_{1}] = \iota_{G_{1}} u - u\iota_{1} \\ & d = \sum_{i=1}^{8} \left(\frac{\partial}{\partial x_{i}} \, dx_{i} \right) = \frac{\partial}{\partial x_{1}} \, dx_{1} + \frac{\partial}{\partial x_{2}} \, dx_{2} + \frac{\partial}{\partial x_{3}} \, dx_{3} + \frac{\partial}{\partial x_{4}} \, dx_{4} + \frac{\partial}{\partial x_{5}} \, dx_{5} + \frac{\partial}{\partial x_{6}} \, dx_{6} + \frac{\partial}{\partial x_{7}} \, dx_{7} + \frac{\partial}{\partial x_{8}} \, dx_{8} \\ & d_{I} : F(M) \to \wedge^{1} M \end{aligned}$$

 $d_{-} = [i_{-} d] = i_{-} d = di$

$$d_{J} = J(d) = \sum_{i=1}^{8} J\left(\frac{\partial}{\partial x_{i}}\right) dx_{i}$$

= $J\left(\frac{\partial}{\partial x_{1}}\right) dx_{1} + J\left(\frac{\partial}{\partial x_{2}}\right) dx_{2} + J\left(\frac{\partial}{\partial x_{3}}\right) dx_{3} + J\left(\frac{\partial}{\partial x_{4}}\right) dx_{4} + J\left(\frac{\partial}{\partial x_{5}}\right) dx_{5} + J\left(\frac{\partial}{\partial x_{6}}\right) dx_{6} + J\left(\frac{\partial}{\partial x_{7}}\right) dx_{7}$
+ $J\left(\frac{\partial}{\partial x_{8}}\right) dx_{8}$

 $d_{J}L = \left(B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{5}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{6}}\right)\right)dx_{1} + \left(B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{6}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{5}}\right)\right)dx_{2} + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{7}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{8}}\right)\right)dx_{3} + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{7}}\right)\right)d4 + \left(-B^{-2}\cos\theta\left(\frac{\partial L}{\partial x_{1}}\right) - B^{-2}\sin\theta\left(\frac{\partial L}{\partial x_{2}}\right)\right)dx_{5} + \left(B^{-2}\cos\theta\left(\frac{\partial L}{\partial x_{2}}\right) - B^{-2}\sin\theta\left(\frac{\partial L}{\partial x_{3}}\right)\right)dx_{6} + \left(-B^{-2}\cos\theta\left(\frac{\partial L}{\partial x_{3}}\right) - B^{-2}\sin\theta\left(\frac{\partial L}{\partial x_{4}}\right)\right)dx_{7} + \left(B^{-2}\cos\theta\left(\frac{\partial L}{\partial x_{4}}\right) - B^{-2}\sin\theta\left(\frac{\partial L}{\partial x_{3}}\right)\right)dx_{8}$ Let $\emptyset_{L} = -d(Jd) = -d\left(d_{J}L\right) = -d\left(\left(B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{5}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{6}}\right)\right)dx_{1} + \left(B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{6}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{5}}\right)\right)dx_{2} + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{7}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{8}}\right)\right)dx_{3} + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{7}}\right)\right)d4 + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{7}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{8}}\right)\right)dx_{3} + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{7}}\right)\right)d4 + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{7}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{8}}\right)\right)dx_{3} + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{7}}\right)\right)d4 + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{7}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{8}}\right)\right)dx_{3} + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{7}}\right)\right)d4 + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{8}}\right)\right)d4 + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{8}}\right)d4 + \left(-B^{2}\cos\theta\left(\frac{\partial L}{\partial x_{8}}\right) + B^{2}\sin\theta\left(\frac{\partial L}{\partial x_{8}}\right)$

$$\begin{aligned} 4734 \quad \text{Ibrahim Yousif J. Abad athman and Abdul Aziz, B. M. Bamed / Ekirk Appl. Math. 107C (2017) 47332-47338 \\ (-B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{1}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{2}}\right)\right) dx_{5} + (B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{2}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{2}}\right)\right) dx_{6} + \\ (-B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{3}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{2}}\right)\right) dx_{7} + (B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{2}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{3}}\right)\right) dx_{6} + \\ dx_{1} = \int_{124}^{2} \left(\frac{\delta h}{\delta x_{1}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{2}}\right) dx_{7} + (B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{2}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{3}}\right)\right) dx_{6} + \\ dx_{1} = \int_{124}^{2} \left(\frac{\delta h}{\delta x_{1}}\right) dx_{1} + \frac{\delta h}{\delta x_{2}} dx_{2} + \frac{\delta h}{\delta x_{3}} dx_{3} + \frac{\delta h}{\delta x_{4}} dx_{4} + \frac{\delta h}{\delta x_{5}} dx_{5} + \frac{\delta h}{\delta x_{6}} dx_{6} + \frac{\delta h}{\delta x_{7}} dx_{7} + \frac{\delta h}{\delta x_{8}} dx_{8} \\ The \quad dy_{1} F(M) \rightarrow \Lambda^{1}M \\ dy_{1} = J(d) = \sum_{i=1}^{2} J\left(\frac{\delta h}{\delta x_{1}}\right) dx_{1} + \left(\frac{\delta h}{\delta x_{2}}\right) dx_{2} + I\left(\frac{\delta h}{\delta x_{3}}\right) dx_{3} + I\left(\frac{\delta h}{\delta x_{4}}\right) dx_{4} + I\left(\frac{\delta h}{\delta x_{5}}\right) dx_{5} + I\left(\frac{\delta h}{\delta x_{6}}\right) dx_{6} + J\left(\frac{\delta h}{\delta x_{7}}\right) dx_{7} \\ + I\left(\frac{\delta h}{\delta x_{8}}\right) dx_{6} dx_{1} + (B^{2}\cos\theta\left(\frac{\delta h}{\delta x_{6}}\right) + B^{2}\sin\theta\left(\frac{\delta h}{\delta x_{6}}\right)\right) dx_{2} + \left(-B^{2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) + B^{2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{2} + \\ \left(-B^{2}\cos\theta\left(\frac{\delta h}{\delta x_{6}}\right) + B^{2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{4} + \left(-B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{7} + \\ \left(B^{2}\cos\theta\left(\frac{\delta h}{\delta x_{6}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{8} + \left(-B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{7} + \\ \left(B^{2}\cos\theta\left(\frac{\delta h}{\delta x_{6}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{8} + \left(-B^{2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{7} + \\ \left(-B^{2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{8} + \left(B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{7} + \\ \left(-B^{2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{8} + \left(-B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{8} + \\ \left(-B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right) - B^{-2}\sin\theta\left(\frac{\delta h}{\delta x_{5}}\right)\right) dx_{8} + \left(-B^{-2}\cos\theta\left(\frac{\delta h}{\delta x_{5}}\right$$

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$$\begin{split} \sum_{i=1}^{s} X^{i} \left[\left(\mathbb{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) + \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{1} \\ & + \left(-\mathbb{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) + \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{2} \\ & + \left(\mathbb{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) + \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{2} \\ & + \left(-\mathbb{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) + \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{4} \\ & + 2\mathbb{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) + 2\mathbb{B}^{-2} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{5} \\ & + \left(\mathbb{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - 2\mathbb{B}^{-2} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) - \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - 2\mathbb{B}^{-2} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{6} \\ & + \left(-\mathbb{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - 2\mathbb{B}^{-2} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) - \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - 2\mathbb{B}^{-2} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{7} \\ & + \left(\mathbb{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - 2\mathbb{B}^{-2} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) - \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - 2\mathbb{B}^{-2} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{7} \\ & + \left(\mathbb{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - 2\mathbb{B}^{-2} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) - \mathbb{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{s} \partial x_{i}} \right) - 2\mathbb{B}^{-2} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{s}} \right) \right) dx_{7} \\ & + \left(\mathbb{B}^{-2} \cos \theta$$

The energy function $E_L = J(\lambda) - L$

$$\begin{split} E_L &= X^1 \left(B^2 \cos \theta \left(\frac{\partial}{\partial x_5} \right) + B^2 \sin \theta \left(\frac{\partial}{\partial x_6} \right) \right) + X^2 \left(B^2 \cos \theta \left(\frac{\partial}{\partial x_6} \right) + B^2 \sin \theta \left(\frac{\partial}{\partial x_5} \right) \right) \\ &+ X^3 \left(-B^2 \cos \theta \left(\frac{\partial}{\partial x_7} \right) + B^2 \sin \theta \left(\frac{\partial}{\partial x_8} \right) \right) + X^4 \left(-B^2 \cos \theta \left(\frac{\partial}{\partial x_8} \right) + B^2 \sin \theta \left(\frac{\partial}{\partial x_7} \right) \right) \\ &+ X^5 \left(-B^{-2} \cos \theta \left(\frac{\partial}{\partial x_1} \right) - B^{-2} \sin \theta \left(\frac{\partial}{\partial x_2} \right) \right) + X^6 \left(B^{-2} \cos \theta \left(\frac{\partial}{\partial x_2} \right) - B^{-2} \sin \theta \left(\frac{\partial}{\partial x_1} \right) \right) \\ &+ X^7 \left(-B^{-2} \cos \theta \left(\frac{\partial}{\partial x_3} \right) - B^{-2} \sin \theta \left(\frac{\partial}{\partial x_4} \right) \right) + X^8 \left(B^{-2} \cos \theta \left(\frac{\partial}{\partial x_4} \right) - B^{-2} \sin \theta \left(\frac{\partial}{\partial x_3} \right) \right) - L \end{split}$$

differential energy function

$$\begin{split} dE_{L} &= \sum_{l=1}^{8} \left[X^{1} \left[B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{5} \partial x_{l}} \right) + 2B \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{5}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{6} \partial x_{l}} \right) + 2B \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{5}} \right) \right] \right. \\ &+ X^{2} \left[- B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{6} \partial x_{l}} \right) + 2B \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{5}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{5} \partial x_{l}} \right) + 2B \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{5}} \right) \right] \\ &+ X^{3} \left[B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{7} \partial x_{l}} \right) + 2B \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{8} \partial x_{l}} \right) + 2B \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{8}} \right) \right] \\ &+ X^{4} \left[- B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{8} \partial x_{l}} \right) + 2B \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{8}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{5} \partial x_{l}} \right) + 2B \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{7}} \right) \right] \\ &+ X^{4} \left[- B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{8} \partial x_{l}} \right) + 2B \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{8}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{7} \partial x_{l}} \right) + 2B \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{7}} \right) \right] \\ &+ X^{5} \left[-B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{1} \partial x_{l}} \right) + 2B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{2}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{2} \partial x_{l}} \right) + 2B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{2}} \right) \right] \\ &+ X^{6} \left[B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{2} \partial x_{l}} \right) - 2B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{2}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{1} \partial x_{l}} \right) - 2B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{2}} \right) \right] \\ &+ X^{7} \left[-B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{3} \partial x_{l}} \right) - 2B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{3}} \right) - B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{4} \partial x_{l}} \right) - 2B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{3}} \right) \right] \\ \\ &+ X^{8} \left[B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{4} \partial x_{l}} \right) - 2B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) \left(\frac{\partial}{\partial x_{4}} \right) - B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{3} \partial x_{l}} \right) - 2B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{l}} \right) \right] \\ \\ &+ X^{8} \left[B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{4} \partial x_{l}} \right) - 2B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{l}} \right) - B^{2}$$

Let = $i_{\lambda}(\phi_L)$ t dE_L

$$\begin{split} & \text{T336} \quad \text{Drahim Yousif } L \text{Abad alrhum and Abdal Aziz, } B. M. \text{Hamed / Elixir Appl. Math. 107C (2017) 47332-47338} \\ &= \sum_{i=1}^{6} X^{i} \left[\left(B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bcso } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{i}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{i}} \right) \right) dx_{1} \\ &+ \left(-B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bcso } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{i}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{n}} \right) \right) dx_{2} \\ &+ \left(B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bcso } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{i}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{n}} \right) \right) dx_{3} \\ &+ \left(-B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{n} \partial x_{i}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{n}} \right) \right) dx_{3} \\ &+ \left(-B^{2} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{n}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{n}} \right) \right) dx_{4} \\ &+ 2 \text{Bcso } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{n}} \right) - B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{n}} \right) \right) dx_{4} \\ &+ \left(-B^{2} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{1}} \right) - 2 B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) - 2 B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{n}} \right) \right) dx_{6} \\ &+ \left(-B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) - 2 B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{k}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{i}} \right) \right) dx_{6} \\ &+ \left(-B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{i} \partial x_{i}} \right) - 2 B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{k}} \right) + 2 \text{Bsin } \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{k}} \right) \right] \\ &+ X^{2} \left[-B^{2} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{k}} \right) + 2 B \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{k}} \right) \right] \\ &+ X^{2} \left[$$

differential energy function

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$$\begin{split} dE_{L} &= \sum_{i=1}^{\circ} \left[X^{1} \bigg[B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{5} \partial x_{i}} \right) + 2 B \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{5}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{6} \partial x_{i}} \right) + 2 B \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{6}} \right) \bigg] \right. \\ &+ X^{2} \bigg[- B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{6} \partial x_{i}} \right) + 2 B \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{6}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{5} \partial x_{i}} \right) + 2 B \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{5}} \right) \bigg] \\ &+ X^{3} \bigg[B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{7} \partial x_{i}} \right) + 2 B \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{7}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{5} \partial x_{i}} \right) + 2 B \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{7}} \right) \bigg] \\ &+ X^{4} \bigg[- B^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{8} \partial x_{i}} \right) + 2 B \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{9}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{7} \partial x_{i}} \right) + 2 B \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{7}} \right) \bigg] \\ &+ X^{5} \bigg[- B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{1} \partial x_{i}} \right) + 2 B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{2} \partial x_{i}} \right) + 2 B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{7}} \right) \bigg] \\ &+ X^{6} \bigg[B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{2} \partial x_{i}} \right) - 2 B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) + B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{1} \partial x_{i}} \right) - 2 B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) \bigg] \\ &+ X^{7} \bigg[- B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{2} \partial x_{i}} \right) - 2 B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{3}} \right) - B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{1} \partial x_{i}} \right) - 2 B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{4}} \right) \bigg] \\ &+ X^{7} \bigg[B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{3} \partial x_{i}} \right) - 2 B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{3}} \right) - B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{4} \partial x_{i}} \right) - 2 B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{4}} \right) \bigg] \bigg] \\ \\ &+ X^{8} \bigg[B^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{4} \partial x_{i}} \right) - 2 B^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{4}} \right) - B^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{3} \partial x_{i}} \right) - 2 B^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{4}} \right) \bigg] \bigg] \\ \\ &- \frac{\partial L}{\partial x_{3}} dx_{i} \bigg]$$

$$\begin{split} &= \sum_{i=1}^{8} \left[X^{1} \left[\mathbf{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{5} \partial x_{i}} \right) + 2\mathbf{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{5}} \right) + \mathbf{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{6} \partial x_{i}} \right) + 2\mathbf{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{6}} \right) \right] \right. \\ &\quad + X^{2} \left[-\mathbf{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{6} \partial x_{i}} \right) + 2\mathbf{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{5}} \right) + \mathbf{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{5} \partial x_{i}} \right) + 2\mathbf{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{5}} \right) \right] \\ &\quad + X^{3} \left[\mathbf{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{7} \partial x_{i}} \right) + 2\mathbf{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{7}} \right) + \mathbf{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{7} \partial x_{i}} \right) + 2\mathbf{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{5}} \right) \right] \\ &\quad + X^{4} \left[-\mathbf{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{8} \partial x_{i}} \right) + 2\mathbf{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{5}} \right) + \mathbf{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{7} \partial x_{i}} \right) + 2\mathbf{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{7}} \right) \right] \\ &\quad + X^{4} \left[-\mathbf{B}^{2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{1} \partial x_{i}} \right) + 2\mathbf{B} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{5}} \right) + \mathbf{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{7} \partial x_{i}} \right) + 2\mathbf{B} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) \right] \\ &\quad + X^{5} \left[-\mathbf{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{1} \partial x_{i}} \right) + 2\mathbf{B}^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) + \mathbf{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{2} \partial x_{i}} \right) + 2\mathbf{B}^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) \right] \\ &\quad + X^{6} \left[\mathbf{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{2} \partial x_{i}} \right) - 2\mathbf{B}^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) - \mathbf{B}^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) \right] \\ &\quad + X^{7} \left[-\mathbf{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{3} \partial x_{i}} \right) - 2\mathbf{B}^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) - \mathbf{B}^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{2}} \right) \right] \\ \\ &\quad + X^{7} \left[-\mathbf{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{3} \partial x_{i}} \right) - 2\mathbf{B}^{-3} \cos \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{3}} \right) - \mathbf{B}^{2} \sin \theta \left(\frac{\partial^{2} L}{\partial x_{4} \partial x_{i}} \right) - 2\mathbf{B}^{-3} \sin \theta \left(\frac{\partial B}{\partial x_{i}} \right) \left(\frac{\partial}{\partial x_{4}} \right) \right] \\ \\ &\quad + X^{8} \left[\mathbf{B}^{-2} \cos \theta \left(\frac{\partial^{2} L}{\partial x_{4} \partial x_{i}} \right) - 2$$

Or

$$-X^{1}B^{2}\cos\theta\left(\frac{\partial^{2}L}{\partial x_{5}\partial x_{i}}\right) + 2X^{1}B\cos\theta\left(\frac{\partial B}{\partial x_{i}}\right)\left(\frac{\partial}{\partial x_{5}}\right) + X^{1}B^{2}\sin\theta\left(\frac{\partial^{2}L}{\partial x_{6}\partial x_{i}}\right) + 2X^{1}B\sin\theta\left(\frac{\partial B}{\partial x_{i}}\right)\left(\frac{\partial}{\partial x_{6}}\right) \\ -X^{1}B^{2}\cos\theta\left(\frac{\partial^{2}L}{\partial x_{5}\partial x_{i}}\right) + 2X^{1}B\cos\theta\left(\frac{\partial B}{\partial x_{i}}\right)\left(\frac{\partial}{\partial x_{5}}\right) + X^{1}B^{2}\sin\theta\left(\frac{\partial^{2}L}{\partial x_{6}\partial x_{i}}\right) + 2X^{1}B\sin\theta\left(\frac{\partial B}{\partial x_{i}}\right)\left(\frac{\partial}{\partial x_{6}}\right) + \frac{\partial L}{\partial x_{1}} dx_{1} = 0 \\ \cos\theta\left[X^{1}\frac{\partial}{\partial x_{i}} + X^{2}\frac{\partial}{\partial x_{i}} + X^{3}\frac{\partial}{\partial x_{3}} + X^{4}\frac{\partial}{\partial x_{4}} + X^{5}\frac{\partial}{\partial x_{5}} + X^{6}\frac{\partial}{\partial x_{6}} + X^{7}\frac{\partial}{\partial x_{7}} + X^{8}\frac{\partial}{\partial x_{8}}\right]B^{2}\frac{\partial L}{\partial x_{6}} + \frac{\partial L}{\partial x_{1}} dx_{1} = 0 \\ -\sin\theta\left[X^{1}\frac{\partial}{\partial x_{i}} + X^{2}\frac{\partial}{\partial x_{i}} + X^{3}\frac{\partial}{\partial x_{3}} + X^{4}\frac{\partial}{\partial x_{4}} + X^{5}\frac{\partial}{\partial x_{5}} + X^{6}\frac{\partial}{\partial x_{6}} + X^{7}\frac{\partial}{\partial x_{7}} + X^{8}\frac{\partial}{\partial x_{8}}\right]B^{2}\frac{\partial L}{\partial x_{6}} + \frac{\partial L}{\partial x_{1}} dx_{1} = 0 \\ \text{The integral curve of the vector filed G , let } \rho: R \to R^{2} \text{ the curve}$$

$$\begin{split} \gamma(\alpha) &= \frac{\partial \alpha}{\partial t} = X^{1} \frac{\partial}{\partial x_{1}} + X^{2} \frac{\partial}{\partial x_{2}} + X^{3} \frac{\partial}{\partial x_{3}} + X^{4} \frac{\partial}{\partial x_{4}} + X^{6} \frac{\partial}{\partial x_{6}} + X^{7} \frac{\partial}{\partial x_{7}} + X^{8} \frac{\partial}{\partial x_{8}} \\ &\quad \cos \theta \left(\frac{\partial}{\partial t}\right) \left(B^{2} \frac{\partial L}{\partial x_{5}}\right) + \sin \theta \left(\frac{\partial}{\partial t}\right) \left(B^{2} \frac{\partial L}{\partial x_{6}}\right) + \left(\frac{\partial L}{\partial x_{1}}\right) = 0 \\ \cos \theta \left[X^{1} \frac{\partial}{\partial x_{i}} + X^{2} \frac{\partial}{\partial x_{i}} + X^{3} \frac{\partial}{\partial x_{3}} + X^{4} \frac{\partial}{\partial x_{4}} + X^{5} \frac{\partial}{\partial x_{5}} + X^{6} \frac{\partial}{\partial x_{6}} + X^{7} \frac{\partial}{\partial x_{7}} + X^{8} \frac{\partial}{\partial x_{8}}\right] B^{2} \frac{\partial L}{\partial x_{6}} \\ &\quad -\sin \theta \left[X^{1} \frac{\partial}{\partial x_{i}} + X^{2} \frac{\partial}{\partial x_{i}} + X^{3} \frac{\partial}{\partial x_{3}} + X^{4} \frac{\partial}{\partial x_{4}} + X^{5} \frac{\partial}{\partial x_{5}} + X^{6} \frac{\partial}{\partial x_{6}} + X^{7} \frac{\partial}{\partial x_{7}} + X^{8} \frac{\partial}{\partial x_{8}}\right] B^{2} \frac{\partial L}{\partial x_{5}} + \frac{\partial L}{\partial x_{2}} dx_{2} = 0 \end{split}$$

$$\begin{aligned} 47338 \quad \text{Ibrahim Yousif I. Abad altrhuman and Abdul Aziz. B. M. Hamed Elixir Appl. Math. 107C (2017) 47332-47338 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial}{\partial x_{k}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial}{\partial x_{k}}\right) + \left(\frac{\partial L}{\partial x_{k}}\right) = 0 \\ -\cos\theta\left[X^1\frac{\partial}{\partial x_{l}} + X^2\frac{\partial}{\partial x_{l}} + X^3\frac{\partial}{\partial x_{3}} + X^4\frac{\partial}{\partial x_{4}} + X^5\frac{\partial}{\partial x_{5}} + X^6\frac{\partial}{\partial x_{6}} + X^7\frac{\partial}{\partial x_{7}} + X^8\frac{\partial}{\partial x_{8}}\right] B^2\frac{\partial L}{\partial x_{7}} \\ +\sin\theta\left[X^1\frac{\partial}{\partial x_{l}} + X^2\frac{\partial}{\partial x_{l}} + X^3\frac{\partial}{\partial x_{3}} + X^4\frac{\partial}{\partial x_{4}} + X^5\frac{\partial}{\partial x_{5}} + X^6\frac{\partial}{\partial x_{6}} + X^7\frac{\partial}{\partial x_{7}} + X^8\frac{\partial}{\partial x_{8}}\right] B^2\frac{\partial L}{\partial x_{8}} + \frac{\partial L}{\partial x_{5}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{7}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + \left(\frac{\partial L}{\partial x_{5}}\right) = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{7}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + \frac{\partial L}{\partial x_{8}} + \frac{\partial L}{\partial x_{8}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{7}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + \frac{\partial L}{\partial x_{8}} + \frac{\partial L}{\partial x_{8}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{7}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + \frac{\partial L}{\partial x_{8}} + \frac{\partial L}{\partial x_{8}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{7}}\right) + \frac{\partial L}{\partial x_{8}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{7}}\right) + \frac{\partial L}{\partial x_{8}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{7}}\right) + \frac{\partial L}{\partial x_{8}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + x^8\frac{\partial}{\partial x_{8}} + X^7\frac{\partial}{\partial x_{7}} + X^8\frac{\partial}{\partial x_{8}} = B^2\frac{\partial L}{\partial x_{1}} + \frac{\partial L}{\partial x_{8}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{8}}\right) + x^8\frac{\partial}{\partial x_{8}} + X^7\frac{\partial}{\partial x_{7}} + X^8\frac{\partial}{\partial x_{8}} + X^7\frac{\partial}{\partial x_{7}} + X^8\frac{\partial}{\partial x_{8}}\right] B^2\frac{\partial L}{\partial x_{1}} + \frac{\partial L}{\partial x_{8}} = 0 \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{1}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{7}}\right) + \left(\frac{\partial L}{\partial x_{8}}\right) = 0 \\ \\ & \cos\theta\left(\frac{\partial}{\partial t}\right) \left(B^2\frac{\partial L}{\partial x_{1}} + X^8\frac{\partial}{\partial x_{8}} + X^7\frac{\partial}{\partial x_{8}} + X^7\frac{\partial}{\partial x_{8}} + X^7\frac{\partial}{\partial x_{7}} + X^8\frac{\partial}{\partial x_{8}}\right] B^2\frac{\partial L}{\partial x_{2}} + \frac{\partial L}{\partial x_{8}} dx_{6} = 0 \\ & \cos\theta\left(\frac{\partial L}{\partial t}\right)$$

Thus

$$\cos\theta\left(\frac{\partial}{\partial t}\right)\left(B^{2}\frac{\partial L}{\partial x_{5}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{2}\frac{\partial L}{\partial x_{6}}\right) + \left(\frac{\partial L}{\partial x_{1}}\right) = 0, \qquad \cos\theta\left(\frac{\partial}{\partial t}\right)\left(B^{2}\frac{\partial L}{\partial x_{6}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{2}\frac{\partial L}{\partial x_{5}}\right) + \left(\frac{\partial L}{\partial x_{2}}\right) = 0$$

$$\cos\theta\left(\frac{\partial}{\partial t}\right)\left(B^{2}\frac{\partial L}{\partial x_{7}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{2}\frac{\partial L}{\partial x_{8}}\right) + \left(\frac{\partial L}{\partial x_{3}}\right) = 0, \qquad \cos\theta\left(\frac{\partial}{\partial t}\right)\left(B^{2}\frac{\partial L}{\partial x_{8}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{2}\frac{\partial L}{\partial x_{7}}\right) + \left(\frac{\partial L}{\partial x_{4}}\right) = 0$$

$$\cos\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{1}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{2}}\right) + \left(\frac{\partial L}{\partial x_{5}}\right) = 0, \qquad \cos\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{2}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{4}}\right) + \left(\frac{\partial L}{\partial x_{7}}\right) = 0, \qquad \cos\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{4}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{3}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{4}}\right) + \left(\frac{\partial L}{\partial x_{7}}\right) = 0, \qquad \cos\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{4}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{3}}\right) + \sin\theta\left(\frac{\partial}{\partial t}\right)\left(B^{-2}\frac{\partial L}{\partial x_{3}}\right) + \left(\frac{\partial L}{\partial x_{8}}\right) = 0 \qquad (9)$$
Conclusions

4. Conclusions

The solutions of the Lagrangian equations (9) are named Conformal Lagrangian Dynamics on Contact 9- Manifolds determined by on the mechanical system triple (TM, g, L) are the paths of vector field J on M. References

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